Column Generation Algorithms for the Capacitated *m*-Ring-Star Problem¹

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may, 2008

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Introduction

Related Problem

Capacitated Vehicle Routing Problem (CVRP)



A Solution for the CVRP



Figure: A solution for the CVRP instance with m = 3, Q = 6 and graph in Figure 1.

Capacitated Vehicle Routing Problem (CVRP)

Given:

- a graph G = (V, E) where $V = \{0\} \cup U$, (depot 0 and a set of customers U);
- a fleet of *m* identical vehicles (each of them having a capacity *Q*);
- costs $c_e \geq 0$, $\forall e \in E$;
- demands $d_i \geq 0, \forall i \in U$.

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The CVRP consists of finding routes for m vehicles such that:

- each route starts and ends at the depot;
- each customer is visited by a single vehicle;
- the total demand of all customers in any route is at most Q, and;
- the sum of the costs of all routes is minimum.

Alternative Solution



Figure: A solution that allows some customers stay outside of all routes.

Definition of the Problem

Capacitated *m*-Ring-Star Problem (CmRSP)

Given:

- a mixed graph $G = (V, E \cup A)$ where $V = \{0\} \cup U \cup W$ (depot 0, a set of customers U and a set of Steiner points W);
- unitary demands;
- integer values m and Q;
- route costs $c_e > 0$, $\forall e \in E = \{(i, j) : i, j \in V\}$, satisfying the triangular inequalities;
- connection costs $w_e > 0$, $\forall e \in A \subseteq \{ij : i \in U, j \in U \cup W\}$.

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The CmRSP consists of finding m Q-ring-stars with minimum costs and covering all customers.

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- a pair (R, S) is a Q-ring-star if:
 - $R \subseteq E$ is a cycle passing by the depot 0;
 - $ij \in S \subseteq A$ such that $i \notin V[R]$ and $j \in V[R]$;
 - $|U \cap (V[R] \cup V[S])| \leq Q.$

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• We say that a Q-ring-star covers a customer i if $i \in V[R] \cup V[S]$.

Examples

Example of a Q-ring-star



Figure: Two 9-*ring-stars* $(\{(0,g), (g,h), (h,i), (i,j), (j,k), (k,0)\}, \{mi, ni, oj, pk, qk\})$ and $(\{(0,a), (a,b), (b,c), (c,0)\}, \{(ec, fc\}).$

Examples

Example of a CmRSP Instance



Example of a *Q*-ring-star



Figure: 8-ring-star for the instance in Figure 5.

Examples

A Solution for the CmRSP instance



Figure: A solution for eil51.tsp with m = 3 e Q = 10.

Integer Programming (IP) Formulation Formulation proposed by Baldacci et al and used into a *branch-and-cut* algorithm.

$$(BC) \quad \min \sum_{e \in E} c_e x_e + \sum_{ij \in A} w_{ij} z_{ij}$$

subject to
$$\sum_{e \in \delta(0)} x_e = 2m \qquad (1)$$
$$\sum_{e \in \delta(i)} x_e = 2y_i, \forall i \in V \setminus \{0\} \qquad (2)$$
$$\sum_{ij \in A} z_{ij} + y_i = 1, \forall i \in U \qquad (3)$$
$$\sum_{ij \in A} z_{ij} + y_i = 1, \forall i \in U \qquad (3)$$
$$\sum_{e \in \delta(S)} x_e \ge \frac{2}{Q} \sum_{i \in U} \sum_{j \in S: ij \in A} z_{ij}, \forall S \subseteq V \setminus \{0\} : S \neq \{\} \qquad (4)$$
$$y \in \{0, 1\}^{|V'|}, z_{ij} \in \{0, 1\}, x_{ij} \in \{0, 1\}. \qquad (5)$$

Motivations

- Practical applications arising in telecommunications and logistics;
 - Large fiber optics networks design;
 - Logistics of product distribution;
 - School bus allocation.
- Just one exact algorithm for CmRSP is reported, to our knowledge;
- In general, set covering models provide tight relaxations.

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Our Objective

• Evaluate the use of a set covering model for the CmRSP together a column generation algorithm to solve it.

(P) min
$$c\lambda$$

s.a. $A\lambda \ge 1, \forall i \in N$ (6)
 $\lambda \in \{0,1\}^p$ (7)

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- Consider just a few number of the columns and **construct other columns implicitly** by solving the *pricing problem*.

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- $\overline{c}_p = c_p \pi A_p$ (π : dual variables corresponding to constraints (6));

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- $\overline{c}_p = c_p \pi A_p$ (π : dual variables corresponding to constraints (6));
- Pricing problem consists of finding $p \in P$ that minimizes \overline{c}_p .

Main Idea

- each column represents a Q-ring-star;
- a solution for the CmRSP consists of *m* columns such that:
 - each customer $i \in U$ is covered by some column;
 - the sum of the costs associated with each column is minimum.

Main Idea

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Figure: Example of a matrix of coefficients in a set covering model.

Set Covering Formulation

Consider

- *P* = {(*R*, *S*)|(*R*, *S*) is a *Q*-ring-star };
- $r^p \in \mathbb{Z}^{|U|+|W|+|E|}_+$ and $s^p \in \mathbb{Z}^{|U|+|A|}_+$: the characteristic vectors of the ring R and of the star S of a ring-star p = (R, S);
- $u_e = 1$, if $e \in E \setminus \delta(0)$, otherwise, $u_e = 2$;
- $c_p = \sum_{e \in R(p)} c_e + \sum_{e \in S(p)} w_e$: the cost of a ring-star p.

Set Covering Formulation

$$\begin{array}{ll} (\mathsf{F1}) & \min \sum_{p \in P} c_p \lambda_p \\ \text{subject to} & \sum_{p \in P} \lambda_p = m \\ & & (8) \\ & \sum_{p \in P} (r_i^p + s_i^p) \lambda_p \geq 1, \forall i \in U \\ & & \sum_{p \in P} \sum_{e \in \delta_i} r_e^p \lambda_p \leq 1, \forall i \in V \setminus \{0\} \\ & & & \sum_{p \in P} r_e^p \lambda_p \leq u_e, \forall e \in E \\ & & & (11) \\ & & & \sum_{p \in P} s_{ij}^p \lambda_p \leq 1, \forall ij \in A \\ & & & & \lambda_p \in \{0,1\}, \forall p \in P \end{array}$$

The Pricing Problem

Consider

- π , μ , ν , β and α : dual variables corresponding to constraints (8), (9), (10), (11) and (12);
- $\tilde{c}_e = c_e \beta_e;$

•
$$\tilde{w}_{ij} = w_{ij} - \alpha_{ij} - \mu_i;$$

•
$$\tilde{p}_i = \mu_i;$$

•
$$\overline{c}_p = \sum_{e \in E} \tilde{c}_e r_e^p + \sum_{ij \in A} \tilde{w}_{ij} s_{ij}^p - \sum_{i \in U} \tilde{p} i r_i^p + \pi.$$

The pricing problem consists of $\min_{p \in P} \overline{c}_p$.

Pricing Problem

Pricing Problem is NP-hard

The profitable tour problem can be reduced in polynomial time to the pricing problem ($W = \emptyset, Q = |V|$, $\tilde{w}_{ij} = \sum_{e \in E} \tilde{c}_e$).

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Alternative

Relax the pricing problem to allow vertex repetition inside a ring-star!



Figure: An example of a relaxed ring-star.

Relaxed Pricing Problem

We analyzed three relaxations:

- BPr: any repetition are allowed;
- BPkc: k-cycles are prohibited inside the component R of a ring-star (R, S);
 - *k*-cycles are cycles with length less than or equal to *k*;
- BPks: k-stream are prohibited inside a ring-star (R, S);
 - A stream is a string of vertices in V[R] and V[S] of a ring-star (R, S) with a fixed order;
 - *k*-streams are cycle with length less than or equal to *k* inside a stream;

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Figure: An example of a 2-cycle and a stream *acdbefab*.

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All these relaxations can be solved in pseudo-polynomial time using dynamic programming.

Solving the Relaxed Pricing Problem



Figure: An example of a (q, j)-walk-star.

• F(j,q): minimum weight of a (q,j)-walk-star.

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Idea

The minimum weight relaxed ring-star can be found by:

$$\min_{j\in V',q\in[1..Q]}F(j,q)+\tilde{c}_{j0}$$

Computing F(j, q)



Computing $\overline{F(j,q)}$

$$F(j,q) = \min \begin{cases} \min_{k \in U: j \in C_k} F(j,q-1) + \tilde{w}_{kj}, \\ \begin{cases} \min_{i \in V, i \neq j} F(i,q-1) + \tilde{c}_{ij} + \tilde{p}_j \\ \min_{i \in V, i \neq j, k \in U: j \in C_k} F(i,q-1) + \tilde{w}_{kj} + \tilde{c}_{ij} \\ \end{cases}, \text{ if } j \in W.$$

where F(0,0) = 0, $F(j,0) = \infty$ and $F(0,q > 0) = \infty$.

Computing F(j,q)

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where
$$F(0,0) = 0$$
, $F(j,0) = \infty$ and $F(0,q > 0) = \infty$.

Complexity

The computation of F(j,q) is O(|V|), so, the relaxed pricing problem can be solved in $O(|V|^2Q)$.

Solving the Relaxed Pricing Problem with *k*-cycle and *k*-stream Elimination

- Similar idea proposed by Irnich and Villeneuve to solve the non-elementary shortest path with resource constraint;
- They used *label setting* algorithm to enumerate all resource feasible paths;
- Some dominance rules are used to remove resource feasible paths that are non-useful (paths that can not be extended to obtain an optimal solution);
- They proposed an algorithm, called Intersection Algorithm, to recognize useful paths.

Digraph of Intersection



Figure: Part of the intersection digraph for k = 3.

We proposed to use a deterministic finite automaton to recognize an useful path.

Computational Environment

- Pentium IV 2.66GHz,900MB of RAM;
- language C, XPRESS optimizer library ^a.

^aXPRESS is a product of Dash Corporation.

Implementation

- We have implemented three *branch-and-price* algorithm, one for each kind of relaxation.
- The BC code is an implementation for the *branch-and-cut* algorithm proposed by Baldacci et al.

Branch-and-Price

Initial basis

We introduced artificial variables with huge costs whose columns form an identity matrix.

To accelerate convergence, we also included a set of columns

corresponding to *ring-stars* that are part of a feasible solution generated by a naïve heuristic inspired in Mauttone et al.

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Branching rule

$$\sum_{e\in\delta(S)}\sum_{p\in P}r_e^p\lambda_p\geq 2\left\lceil\frac{|\{i\in U:C_i\subseteq S\}|}{Q}\right\rceil, S\subseteq V\setminus\{0\}, S\neq\emptyset.$$

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Node selection

The classical best-bound strategy is used to select the next node to be explored during the enumeration procedure.

Bounding

- No heuristics were developed to compute feasible solutions during the enumeration. Primal bounds must correspond to IP solutions.
- Dual bounds are directly obtained from the linear relaxations or from Lasdon's formula.

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Pricing

- all columns with negative reduced cost associated to non relaxed ring-stars;
- for each j ∈ V \ {0}, the most negative reduced cost column related to the minimum weight relaxed (q, j)-walk-star.

Table: Comparison between BPr, BP3c, BP3s, BP3sA and BC codes.

	$\texttt{BPr}~\times~\texttt{BP3c}$				BP3c \times BP3s		
instance	GAP	TIME	OPT	-	GAP	TIME	OPT
eil40.tsp	1.0	2.8	2/8		*	1.6	1/9
eil51.tsp	1.0	1.4	0/2		0.4	19.9	4/6
eil64.tsp	1.4	*	0/0		1.3	*	4/4
eil76.tsp	0.6	*	1/1		2.5	48.7	0/1
	BP3s \times BP3sA			$BC \times BP3sA$			
instance	GAP	TIME	OPT		GAP	TIME	OPT
eil40.tsp	*	3.3	0/9		*	0.4	0/9
eil51.tsp	0.2	3.5	0/6		-0.6	0.6	0/6
eil64.tsp	0.1	2.3	0/4		0.1	0.4	0/4
eil76.tsp	0.2	2.4	0/1		11.8	*	1/1



Figure: Comparison between BP3s and BP3sA codes.



Figure: Comparison between BP3sA and BC.



(a) Percentage of increase in lower (b) Total of instances with best lower bound at the root node bound at the root node

Figure: Lower bound comparative between BP3sA and BC.

Preliminary Results for Branch-and-Cut-and-Price (BCP)

Table: Comparison between BP3sA, BC and BCP

	$BP3sA \times BCP$			$\texttt{BC}~\times~\texttt{BCP}$		
instance	GAP	TIME	OPT	GAP	TIME	OPT
eil40.tsp	*	1.7	0/9	*	2.6	0/9
eil51.tsp	0.9	1.8	1/7	0.0	0.8	0/7
eil64.tsp	0.2	2.2	0/4	0.1	2.5	0/4
eil76.tsp	0.1	1.0	0/1	0.2	*	1/1

Computational Results

Preliminary Results for Branch-and-Cut-and-Price (BCP)



Figure: Comparison between BCP and BC.

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Computational Results

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- more stringent relaxations lead to higher speedups in running times (early pruning);
- Using deterministic finite automaton was important to reduce the pricing time;
- Set covering model presented better dual bounds;
- The BP3sA and BC do not dominate each other and some instances are better suited for one or the other algorithm.

Further Works

- Introduce primal heuristic (to improve primal dual);
- Remove columns during branch-and-price (to reduce LP time);
- Add strong-branching (to obtain better dual bound early);
- Implement a *branch-and-cut-and-price* (on going).

The End

Questions?